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Empirical Mode Decomposition for Modeling of Parallel Applications on Intel Xeon Phi Processors



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Acknowledgements











Outline



- 1. Motivation
- 2. Empirical Mode Decomposition
- 3. Model Construction
- 4. Experiment Overview
- 5. Measured vs. Modeled Results
- 6. Future Directions



Motivation

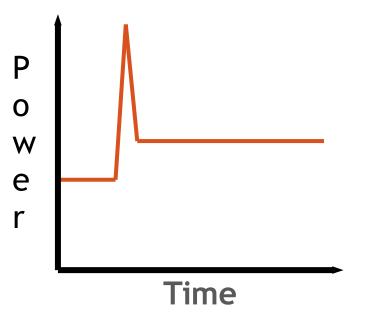
- n Existing models primarily focus on performance
 - Number crunching was the bottleneck until the mid-2000's
 - Current hardware bottlenecks include
 - n Memory bandwidth
 - n Power usage

- n There is a need for a new model which includes both power and performance
 - High-level abstraction of hardware and application
 - Focus on power and energy consumption

n



Typical cluster power draw when fully occupied



Ellsworth et. al., 2016

Modeling Multi-Core Energy

Not easily extendable to real-world applications



n Roofline

- Operational intensity
- Support for power and energy
 - Vuduc et al., 2014

n Device Specific

- Advanced knowledge of the architecture
- Instruction-level modeling
 - Shao and Brooks, 2009

n McPAT

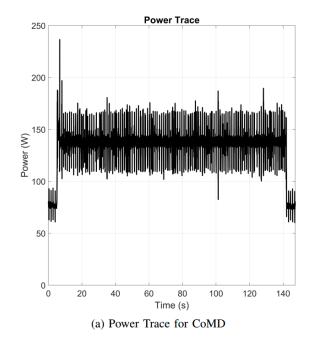
- Expert knowledge of the architecture
- State-of-the-art modeling framework
 - Li et al., 2009

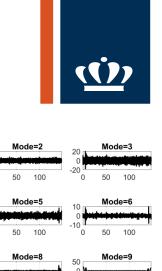
Empirical Mode Decomposition (EMD)

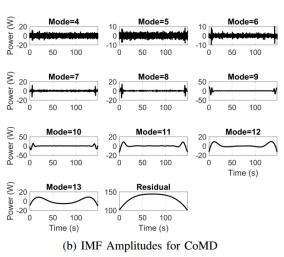
Decompose a non-parametric non-stationary timeseries into intrinsic mode functions and the residual trend

[N. Huang, et al. *The empirical mode decomposition and the Hilbert spectrum for nonlinear and non-stationary time series analysis,* 1998.]

- n Used in many scientific fields:
 - n Medicine, Finance, Geosciences







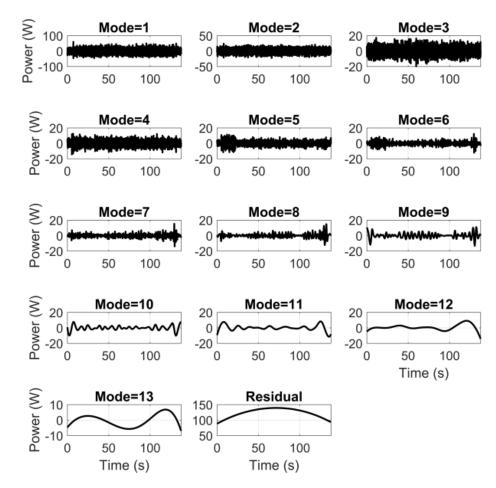
n Used to uncover correlations in physical phenomena

Empirical Mode Decomposition (cont'd)

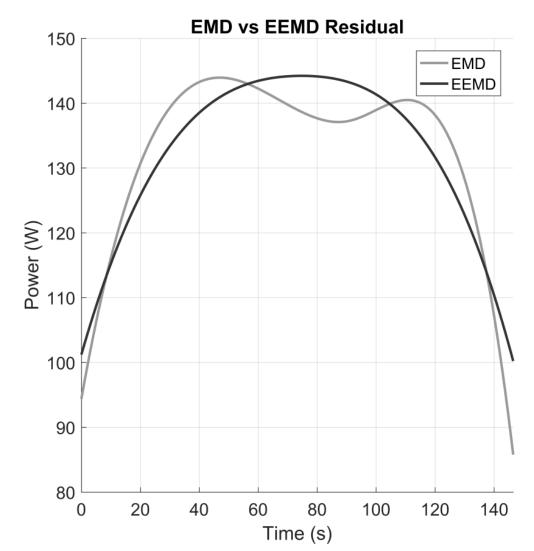


n Power draw is a complex physical response to the workload of a given application on the hardware

- n Final result of EMD is the residual trend
 - removed row, this trend shows power consumption over time when high-frequency interactions have been removed
 - n Can be modeled using quadratic equation



Ensemble Empirical Mode Decomposition (EEMD)



- n EMD strongly depends on variations in frequency and amplitude of the time-series to decompose all IMFs
 - n EEMD alleviates this dependency

n EEMD [Wu & Huang, 2009]

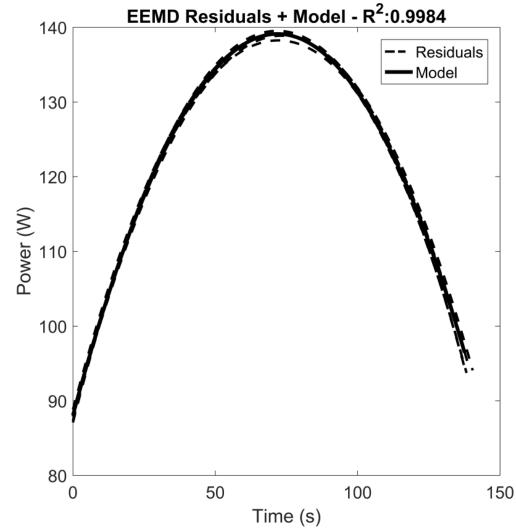
- n Uniform white noise is added to the source signal before IMFs are decomposed
- n EMD is performed on this new signal many times
- The resulting IMFs are the mean of all the IMFs



Model Construction



- 1. Choose an execution configuration
 - n E.g., Number of cores, power limit
- 2. Run a few times (n)
 - Obtain Power Trace using Measurement Procedure
 - 2. Apply EEMD
 - n 5 W @ N = 50
 - 3. Collect Residual Trend
- 3. Fit quadratic model to the *n* residuals
 - Including idle power measurements in the power trace enables a quadratic fit

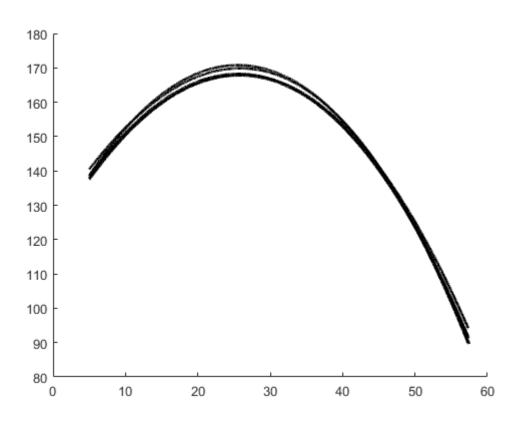


Model Construction (cont'd)

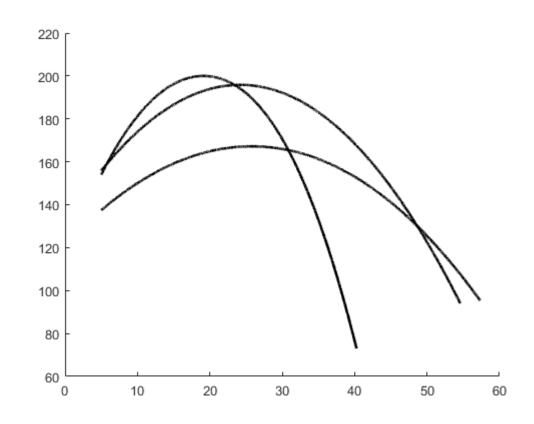
Suppose no idle power measurements







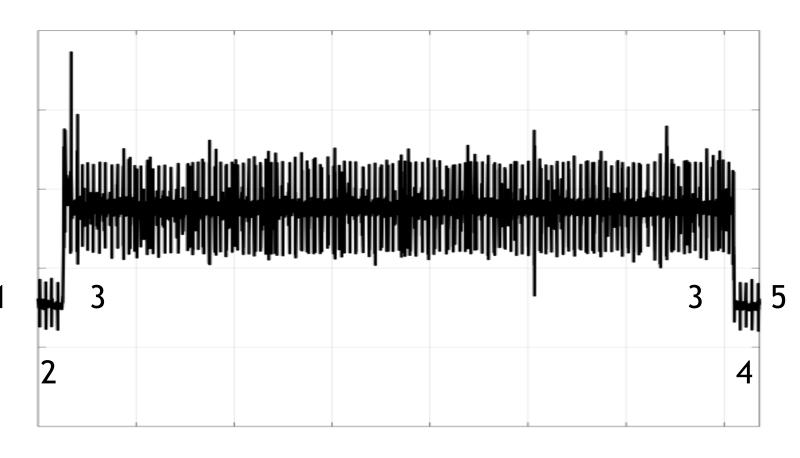
Varying # Cores



Measurement Procedure

- 1. Begin power sampling
 - n Sandia Power API
 - n RAPL via Linux Power Capping Framework
 - n 5ms sampling rate
 - n Power = DRAM + Core
- 2. Wait 5 seconds
 - Capture idle power
- 3. Begin application Wait for end
- 4. Wait 5 seconds
 - n Capture idle power
- 5. End power sampling





Experiment Specifications

Computing Platform

- n Rulfo single-node system at Old Dominion University
- n Xeon Phi Processor 7210
 - n 64 cores @ 1.3 GHz per core:
 - n 4 HW threads
 - n 2 512-bit VPU
 - n 32 MB L2 cache
 - n 16 GB MCDRAM
 - n 215 Watt TDP

n Application configurations

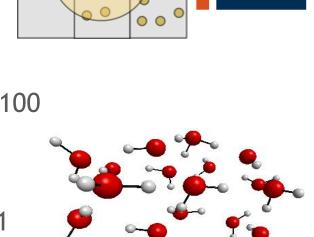
n CoMD

n Force Kernel: LJ, EAM

n Problem Sizes: 60, 80, 100

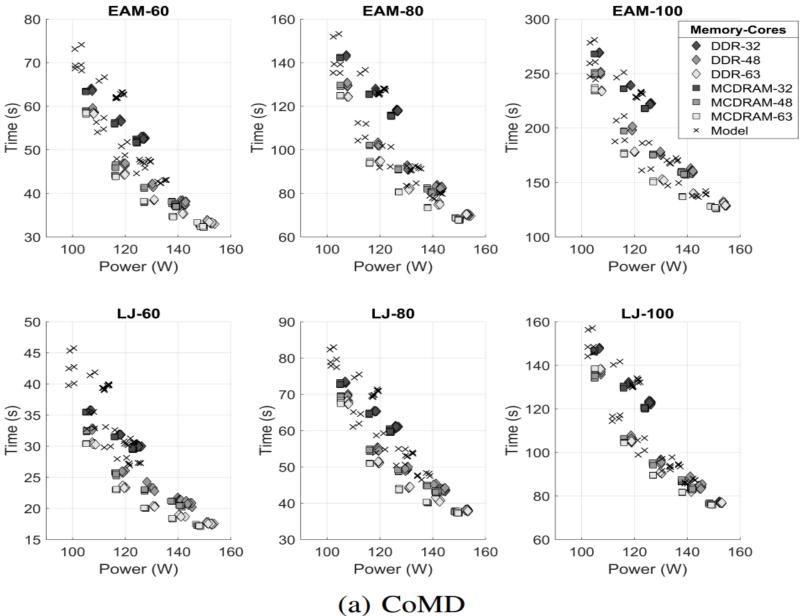


n Problems: 1L2Y, 20w, S265, S301



- n Hardware configurations
 - Number of Cores: 32, 48, 63
 - n 1 core dedicated to power measurements
 - n DRAM Memory: DDR, MCDRAM (flat)
 - n Power Limiting: 140, 130, 120, 110, 100, 90

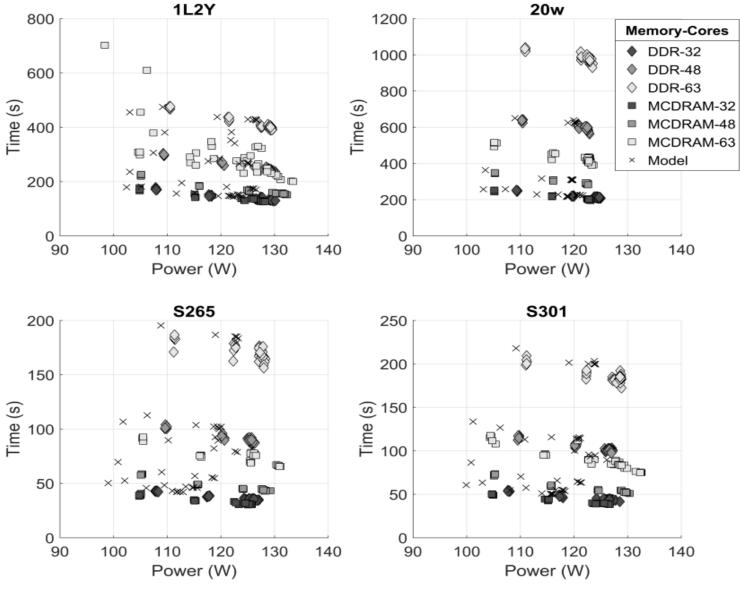
Modeled vs. Measured Results (CoMD)





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Modeled vs. Measured Results (GAMESS)



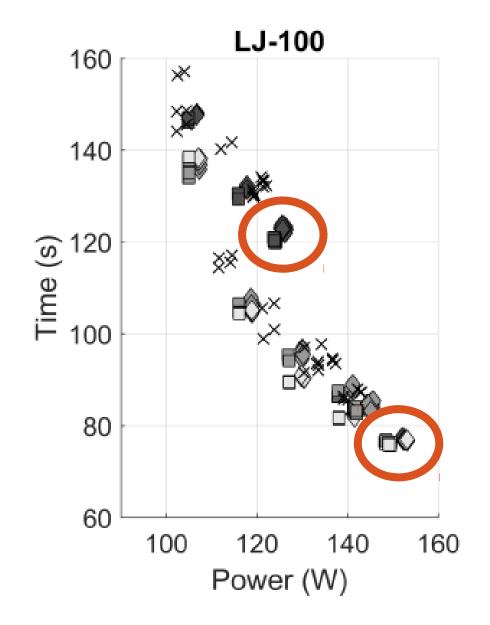


(b) GAMESS

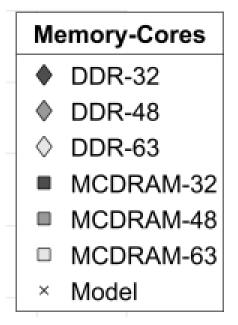
Measured Results (MCDRAM)

MCDRAM (flat-mode) provides best performance vs. DDR

- n 1-2% energy savings
- n 1-3W power reduction
- n 1-2% time reduction



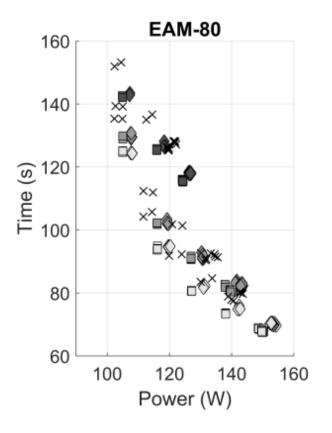




Measured Results (CoMD & GAMESS)

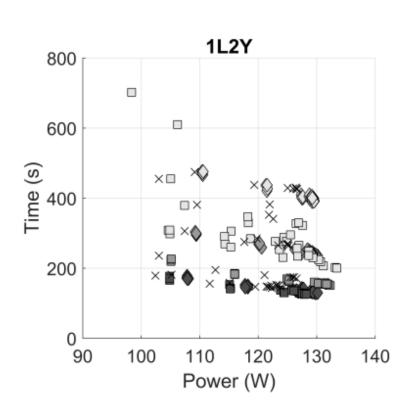
CoMD

- n Max cores (63)
 - n To max performance
- n 120W power limit



GAMESS

- n Min cores (32)
 - n To max memory bandwidth
- Default power (215W)





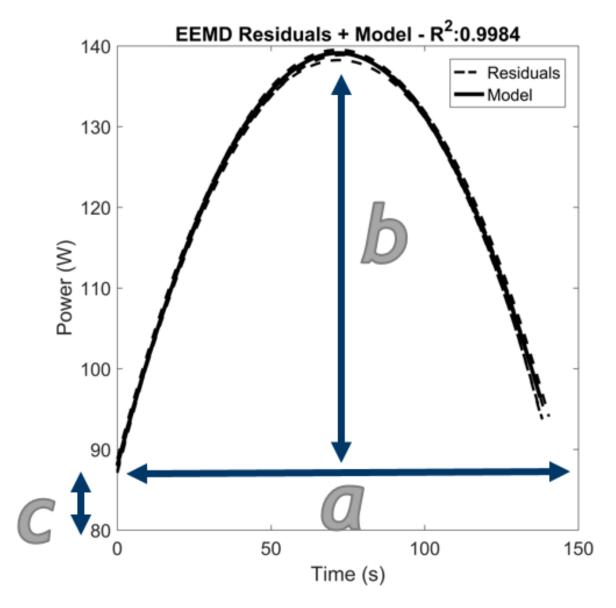
Quadratic Model

n Time

- n Coefficient a < 0</pre>
- Direct relationship to |a|

n Power

- n Coefficient b > 0 (max power)
- n Coefficient c > 0 (min power)
- n Direct relationship with |b| & |c|



Model Error

$$Error = \frac{measured - modeled}{measured}$$

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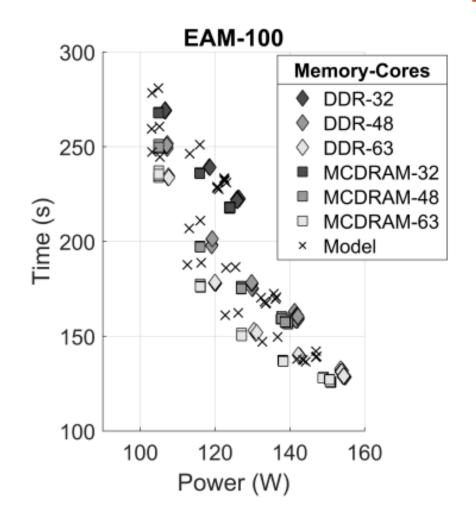
Power

- n No more than 10% error
- n Is under-estimated
 - n Residual does not go up to max power draw

Time

- n No more than 15% error
- n Is over-estimated
 - n Model time assumes powerdraw at the start and end ofthe trace is equal

CoMD

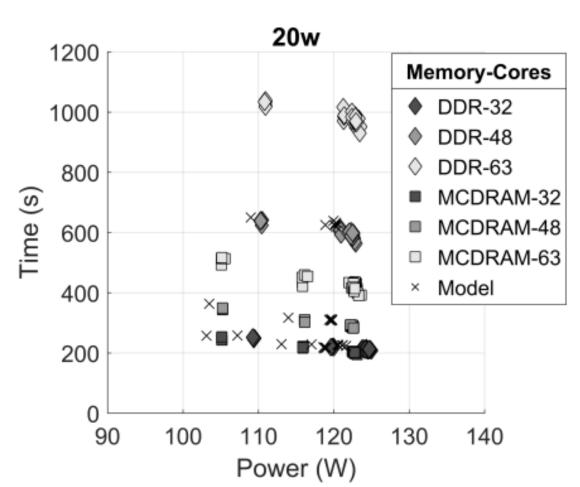


Model Error (cont'd)

$$Error = \frac{measured - modeled}{measured}$$

Energy

- n 5% 30% error
- Shorter traces incur higher error than longer traces
 - n Short trace < 100 seconds
 - n Long trace > 100 seconds



GAMESS

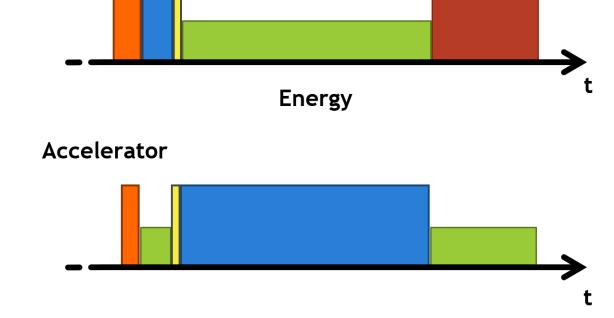
Advantages of Modeling Energy with EMD

Host



Generality

- Applies to any hardware architecture
 - n Multi-core CPU, Accelerator, or Hybrid
 - n Single-node, Multi-node
- Applies to any software application
 - n Benchmark
 - n Kernel
 - n Mini-App
 - n Real-World



Phase Model

Lawson, Sundriyal, MS, and Shen. 2015. Modeling performance and energy for applications offloaded to Intel Xeon Phi.

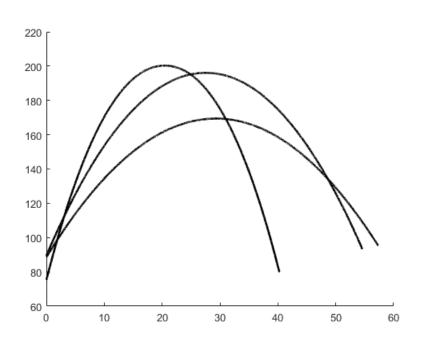
Advantages of Modeling Energy with EMD (cont'd)

Rigorous

- n Guided specific measurement procedure
- n EMD residual fits to quadratic function

Ease-of-Use

- Only requires a power trace to produce a model
- No advanced knowledge of application or hardware required



Performance

- Manageable overhead
 - n Known to increase with trace size
 - n Alleviated by running EMD on segments



Future Directions

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n Refine model construction and definition

n Investigate applicability of IMF modes

n Enhance the model with predictive capabilities

References

- D. Ellsworth, T. Patki, M. Schulz, B. Rountree and A. Malony, "A Unified Platform for Exploring Power Management Strategies," 2016 4th International Workshop on Energy Efficient Supercomputing (E2SC), Salt Lake City, UT, 2016, pp. 24-30.
- Z. Wu and N. Huang. Ensemble empirical mode decomposition: A noise-assisted data analysis method. Advances in Adaptive Data Analysis, 01(01):1-41, 2009.
- G. Lawson, V. Sundriyal, M. Sosonkina, and Y. Shen. 2015. Modeling performance and energy for applications offloaded to Intel Xeon Phi. In *Proceedings of the 2nd International Workshop on Hardware-Software Co-Design for High Performance Computing* (Co-HPC '15). ACM, New York, NY, USA, , Article 7 , 8 pages. DOI: https://doi.org/10.1145/2834899.2834903

n



Questions?

MCDRAM



Multi-Channel DRAM

- Stackable Memory
- n 16 GB
- n 3 Modes of Operation
 - n Flat
 - n Cache
 - n Hybrid

n Flat-Mode (this work)

- n Use MCDRAM over traditional DDR
- n numactl -membind 1
 ./<application command>

n Cache-Mode

- n L3 Cache Level
- Specific variables (in code) assigned to MCDRAM
 - n Requires explicit code changes

n Hybrid-Mode

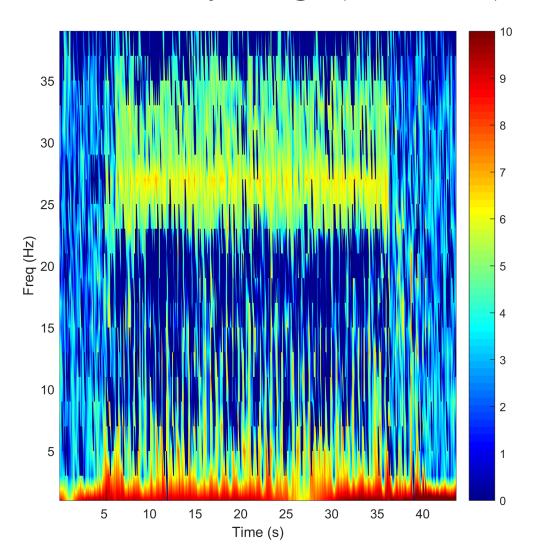
Split MCDRAM 25/75 or 50/50 between Flat and Cache modes



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EMD / HHT Analysis

CoMD on Ivy-Bridge (max cores)



GAMESS on KNL (max cores)

